

Google “AxiSEM3D Github”



# Global wavefield modelling in 3-D crustal models using **AxiSEM3D**

**Kuangdai Leng<sup>1</sup>, Tarje Nissen-Meyer<sup>1</sup>, Kasra Hosseini<sup>1</sup>,**  
**Martin van Driel<sup>2</sup>, and David Al-Attar<sup>3</sup>**

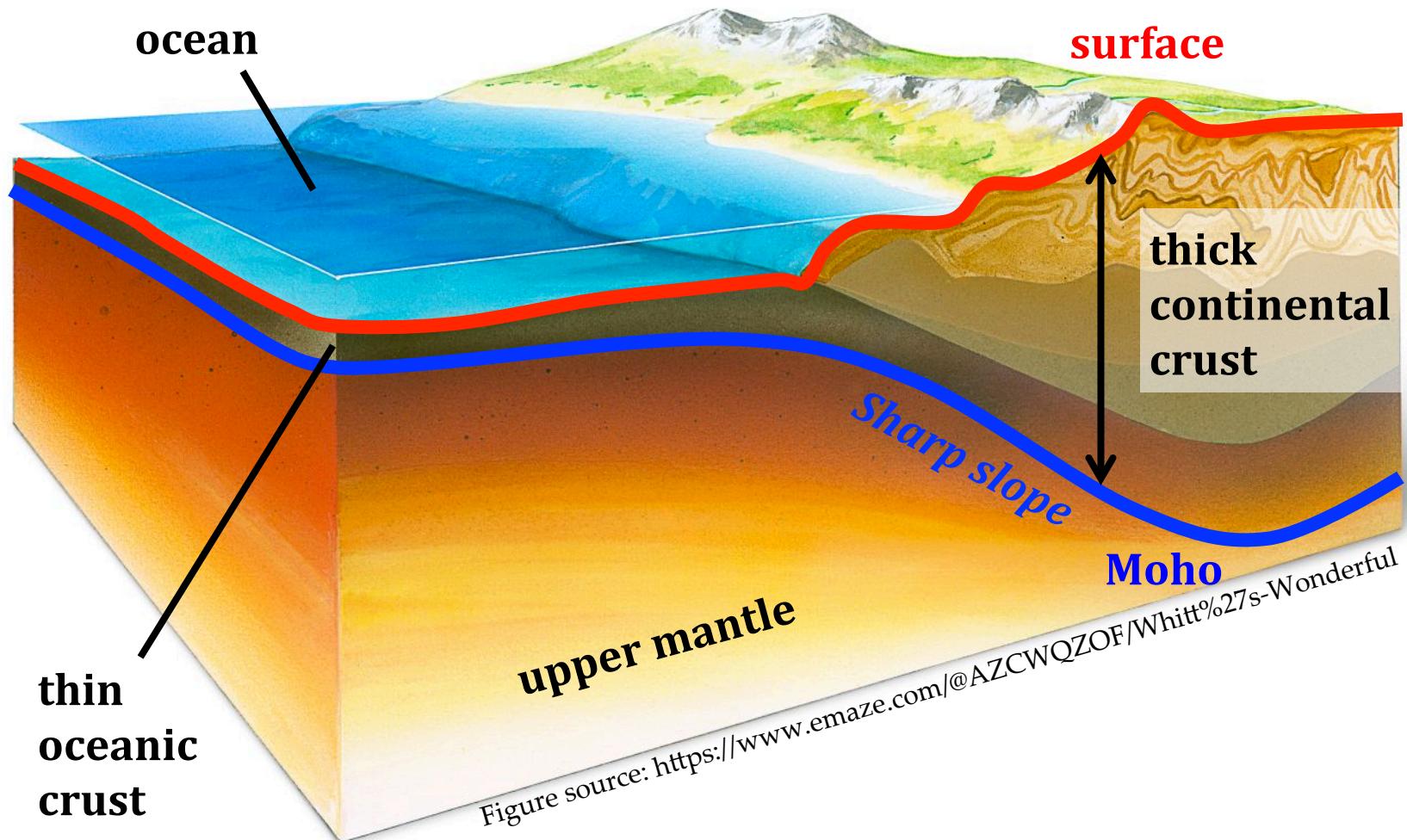
1. Department of Earth Science, University of Oxford.

2. Department of Geophysics, ETH Zurich

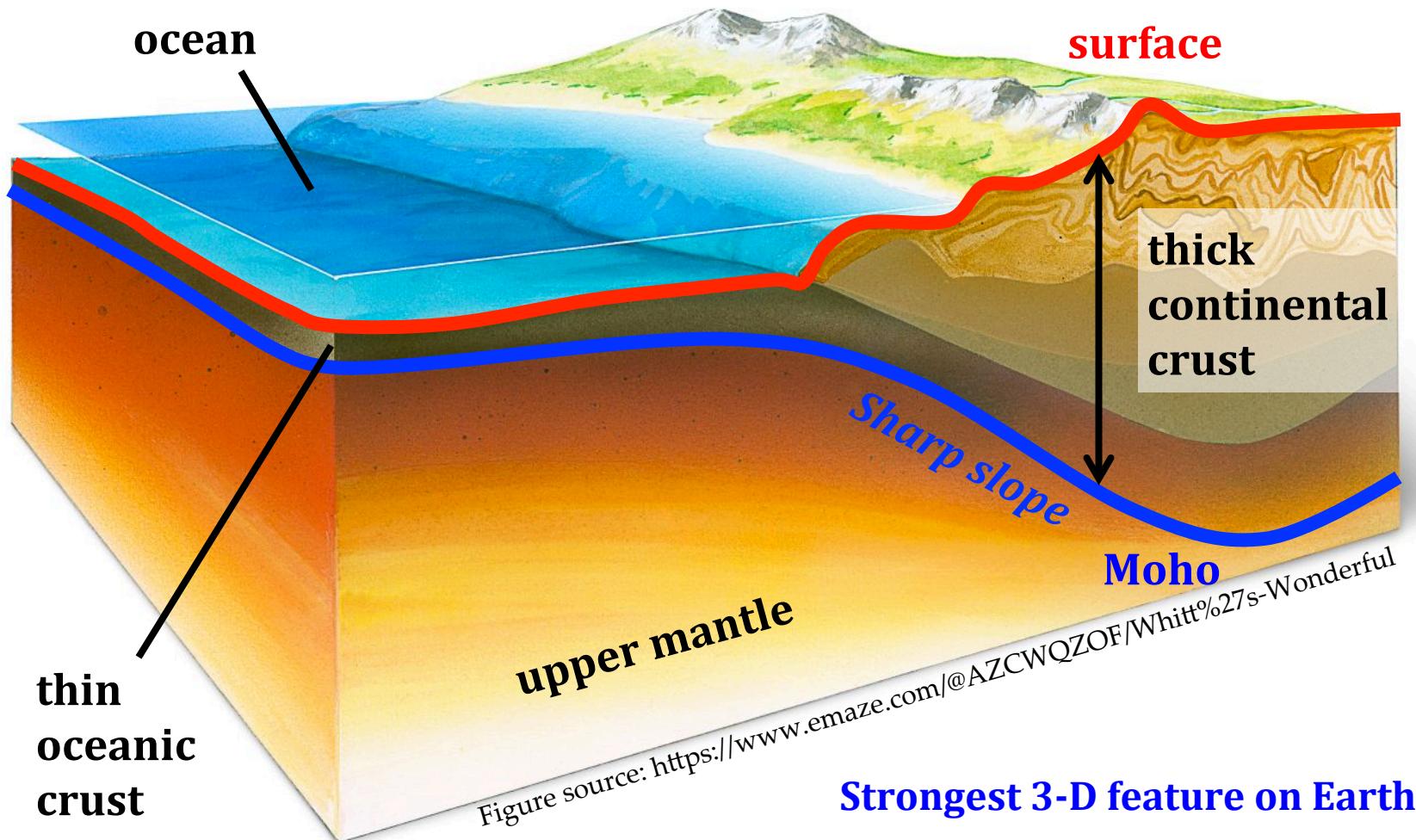
3. Department of Earth Science, University of Cambridge

British Seismology Meeting  
April 2017, Reading, UK

# Earth's crust in nature



# Earth's crust in nature

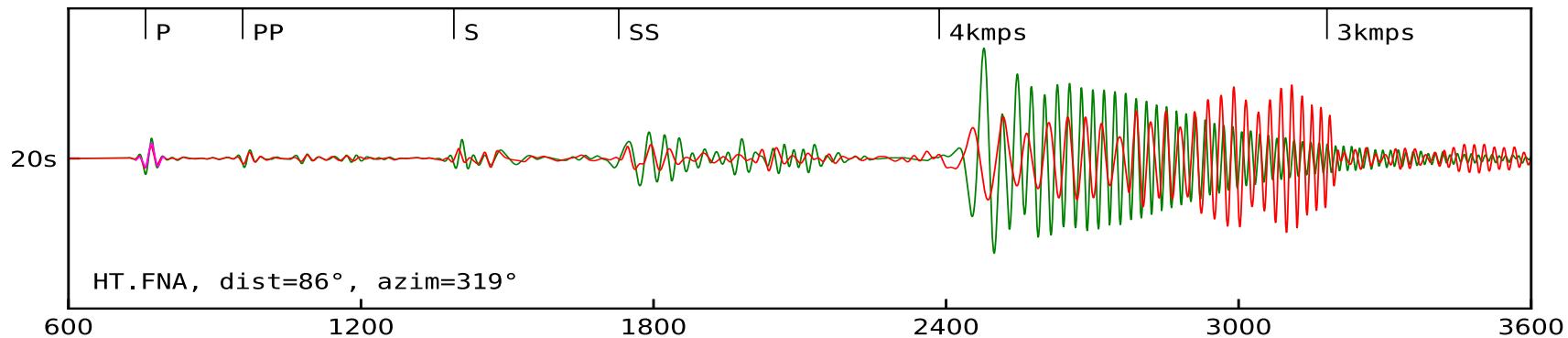


**Strongest 3-D feature on Earth**

- Crustal thickness ranges from 5 to 80 km, with sharp transitions at ocean-continent boundaries
- Velocities varies fast both horizontally and vertically

# Earth's crust in wave propagation

- 3-D crust **RESHAPES** the surface waves

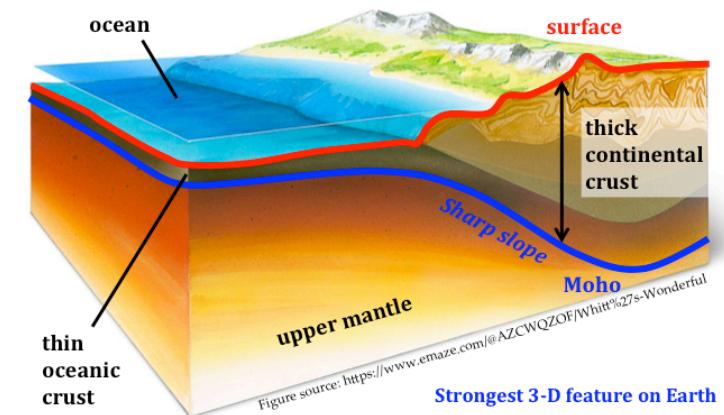
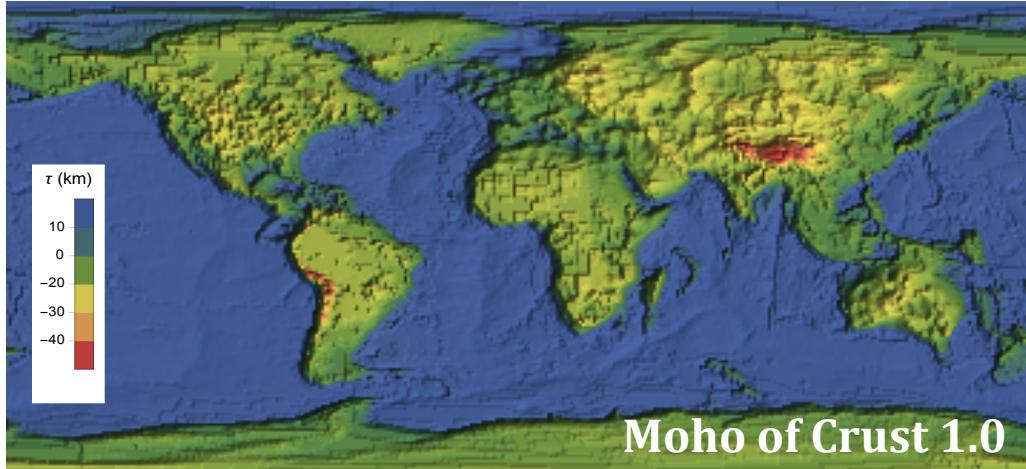


- Realistic **forward simulations** of surface waves is a fundamental issue
  - structural inferences at all scales (subduction zones, sediment basins, ...)
  - earthquake sources
  - nuclear monitoring
  - site effects and hazard assessments
- For seismic **inverse problems**, the Born approximation based on 1-D reference models ceases to work (*Zhou et al., 2005*)
  - surface wave tomography
  - noise tomography
  - travel time and waveform corrections
  - dispersion measurements

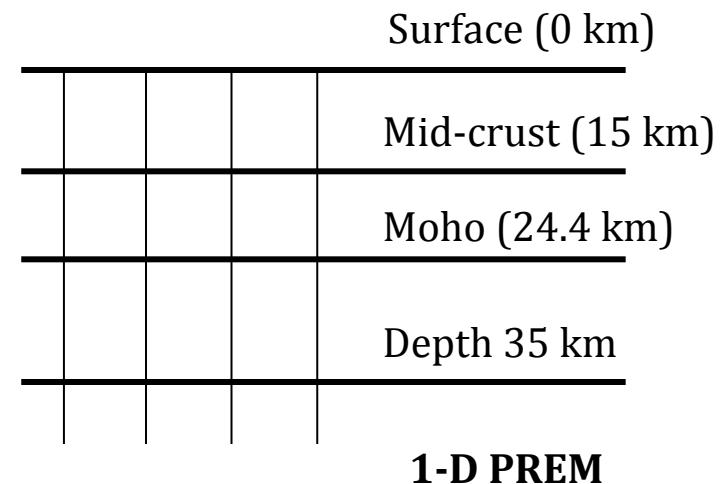
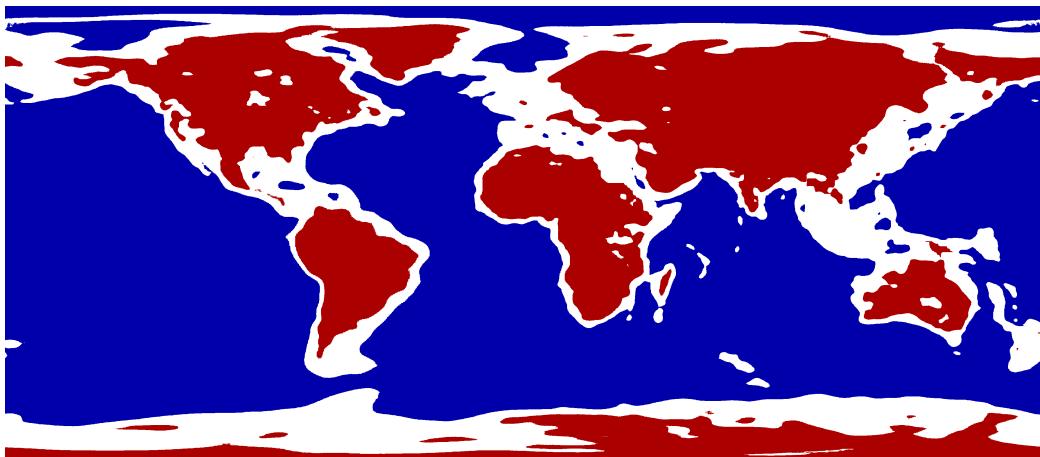
$$\mathbf{G} \cdot \delta\mathbf{m} = \delta\mathbf{d}$$

# Crust implementation in 3-D methods

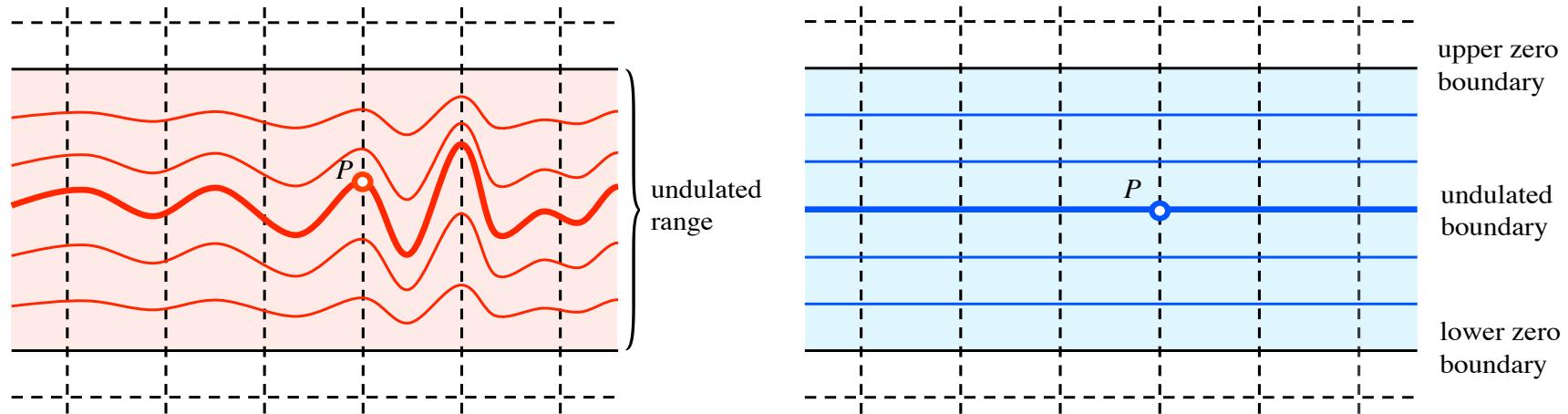
- Most challenging aspect in wavefield modelling



- Implementation in SPECFEM3D\_GLOBE (*Komatitsch and Tromp, 2002*)



# Crust implementation in AxiSEM3D



Geometric mapping:  $\tau = \tau(r, \theta, \phi) = \begin{cases} \frac{\tau_{\text{surf}} - \tau_{\text{moho}}}{R_{\text{surf}} - R_{\text{moho}}} (r - R_{\text{moho}}) + \tau_{\text{moho}} & r \geq R_{\text{moho}} \\ \frac{\tau_{\text{moho}}}{R_{\text{moho}} - R_{\text{base}}} (r - R_{\text{base}}) & r < R_{\text{moho}} \end{cases}$

Jacobian:  $\mathbf{H} = [\mathbf{I} + \nabla(\tau \hat{\mathbf{r}})]^T$

Particle relabelling transformation (*Al-Attar and Crawford, 2016*):

$$\tilde{\rho} = \rho \det \mathbf{H}, \quad \tilde{\mathbf{C}} = \mathbf{H}^{-1} \cdot \mathbf{C} \cdot \mathbf{H}^{-T} \det \mathbf{H}$$

# Crust implementation in AxiSEM3D

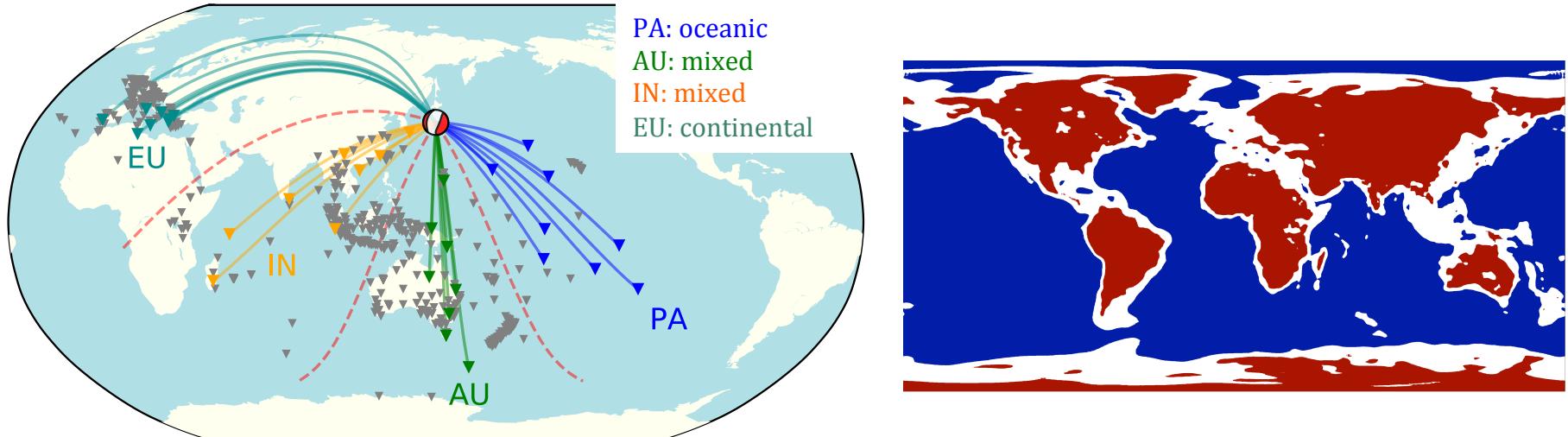
- **Particle relabelling transformation**
  - The two models are equivalent in terms of wave propagation
  - Frequency independent (compared to Homogenization, *Capdeville et al. 2013*)
  - Geometric complexity → Material complexity (anisotropy)
- **Pros and Cons**

	SPECFEM	AxiSEM3D
<b>Moho discontinuity</b>	<b>patched</b>	<b>integrated</b>
<b>Robustness</b>	<b>weak</b>	<b>Strong</b>
<b>Extensibility (CMB, transition zone, Mars)</b>	<b>difficult (hardcoded for Earth's crust)</b>	<b>easy</b>
<b>time step</b>	<b>similar to PREM crust</b>	<b>half of PREM crust</b>

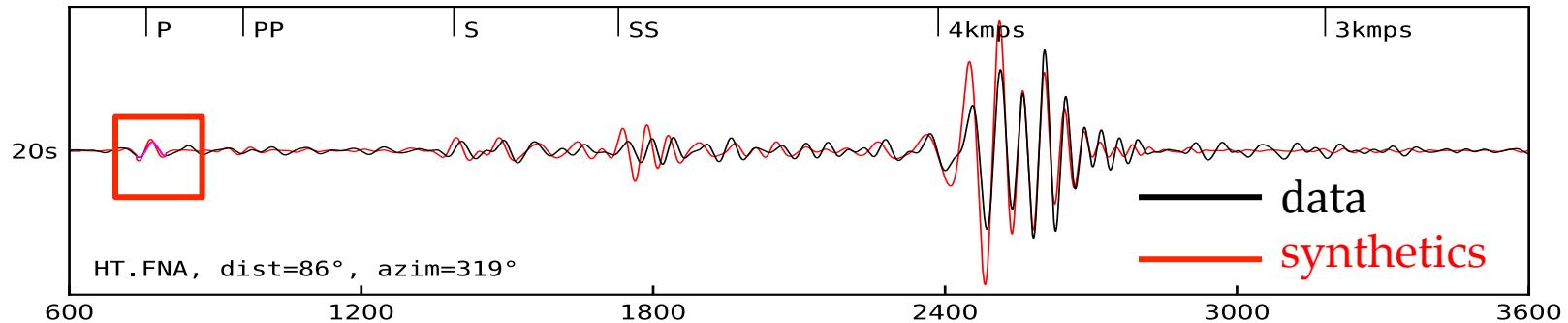
- Even with a smaller time step, AxiSEM3D is still 1-2 orders of magnitude faster than 3-D methods such as SPECFEM

# Comparison to data

- No reference solution for global wave propagation with crustal models
- Model: **Crust 1.0** for the crust, **S40RTS** for the mantle, Period = 10s
- Source (Japan, 20 km) and stations (620 in total)

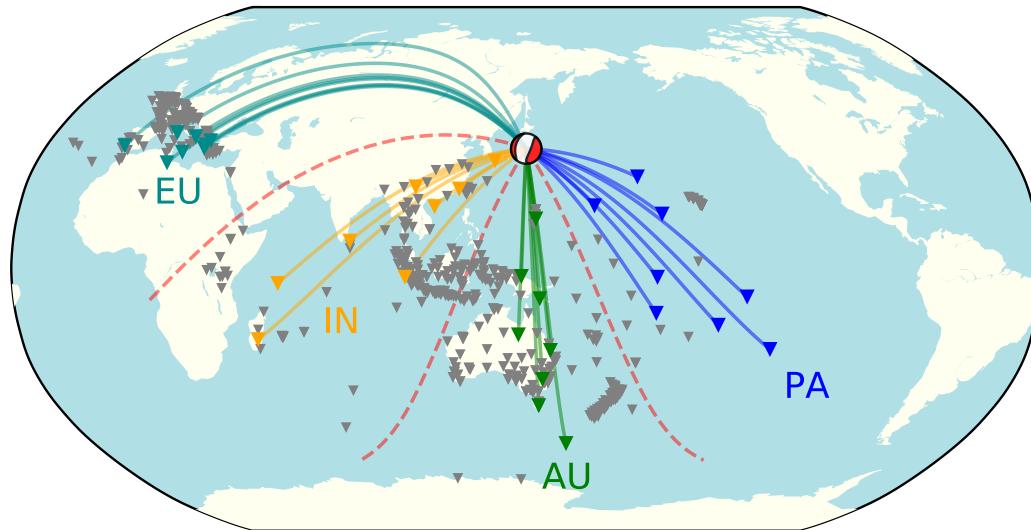


- Processing (filtered at 40 s and 20 s before comparison)



# Comparison to data – Summary

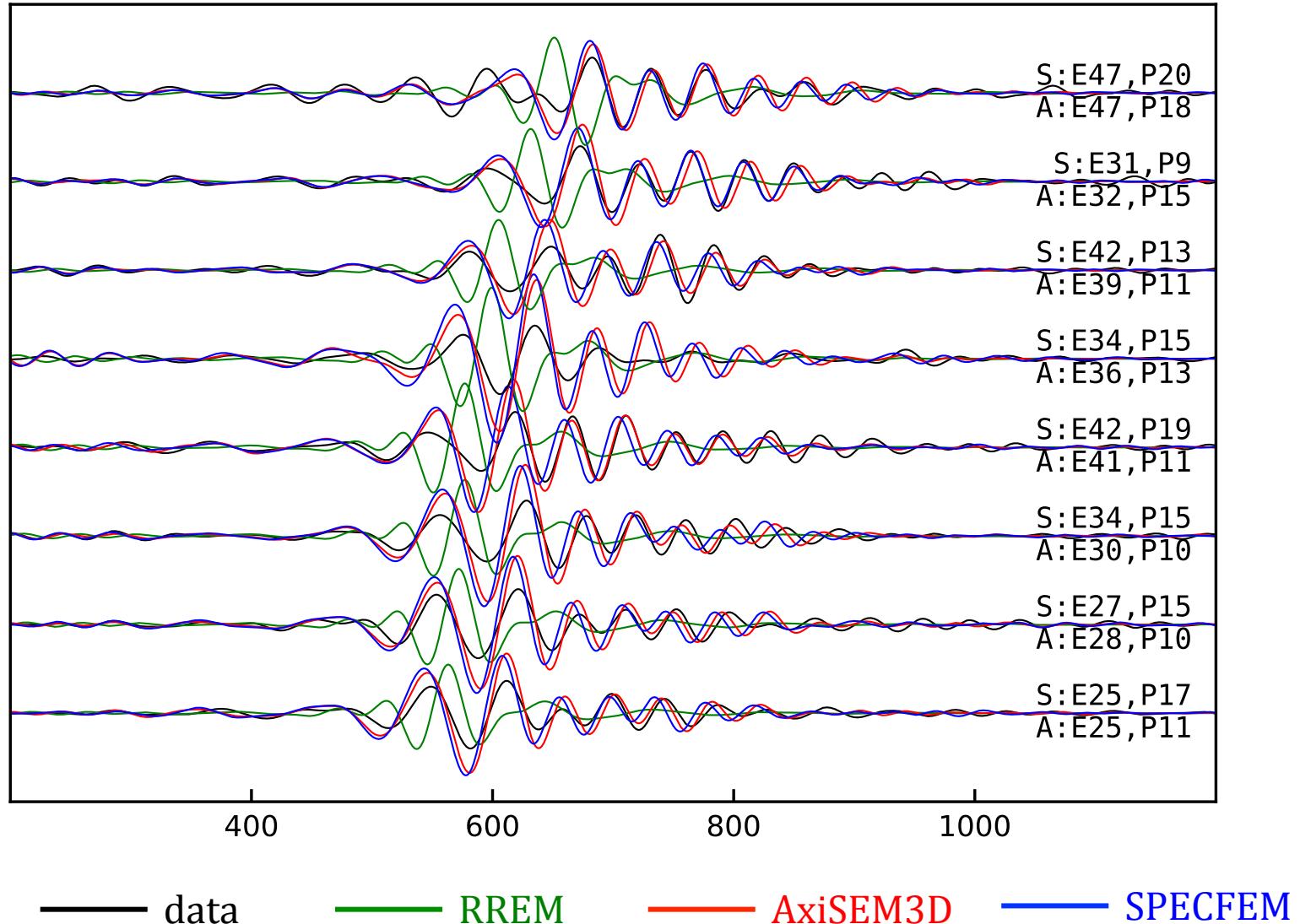
- The 3-D model fits the data much better than PREM does.
- AxiSEM3D is more accurate for PA, AU and IN.
- SPECFEM and AxiSEM3D have very similar accuracy for EU.



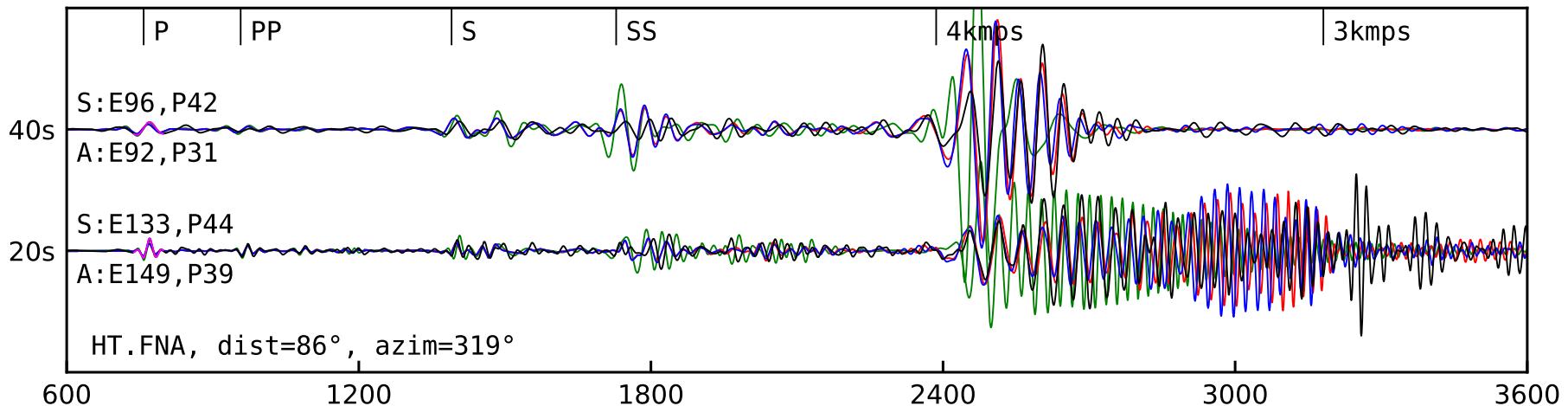
PA: oceanic  
 AU: mixed  
 IN: mixed  
 EU: continental

	ALL, 40 s	PA, 40 s	AU, 40 s	IN, 40 s	EU, 40 s	ALL, 20 s	PA, 20 s	AU, 20 s	IN, 20 s	EU, 20 s
total number of stations	616	53	210	171	182	616	53	210	171	182
AxiSEM3D fits better	65%	96%	67%	64%	53%	61%	82%	71%	52%	49%
Ave. $m_e$ SPEC / Axi3D	0.117	0.094	0.149	0.100	0.102	0.317	0.122	0.284	0.298	0.435
Ave. $m_e$ SPEC / data	0.609	0.293	0.701	0.701	0.510	0.868	0.496	1.047	0.948	0.707
Ave. $m_e$ Axi3D / data	0.601	0.247	0.694	0.679	0.511	0.851	0.461	1.038	0.954	0.666
Ave. $m_e$ PREM / data	0.723	0.705	0.785	0.783	0.602	1.060	1.076	1.011	1.035	1.134
Ave. $m_p$ SPEC / Axi3D	0.108	0.119	0.143	0.064	0.105	0.437	0.282	0.517	0.384	0.447
Ave. $m_p$ SPEC / data	0.398	0.507	0.493	0.426	0.231	0.514	0.560	0.588	0.498	0.432
Ave. $m_p$ Axi3D / data	0.371	0.406	0.454	0.413	0.230	0.485	0.402	0.519	0.489	0.447
Ave. $m_p$ PREM / data	0.590	0.600	0.493	0.532	0.754	0.587	0.594	0.570	0.569	0.621

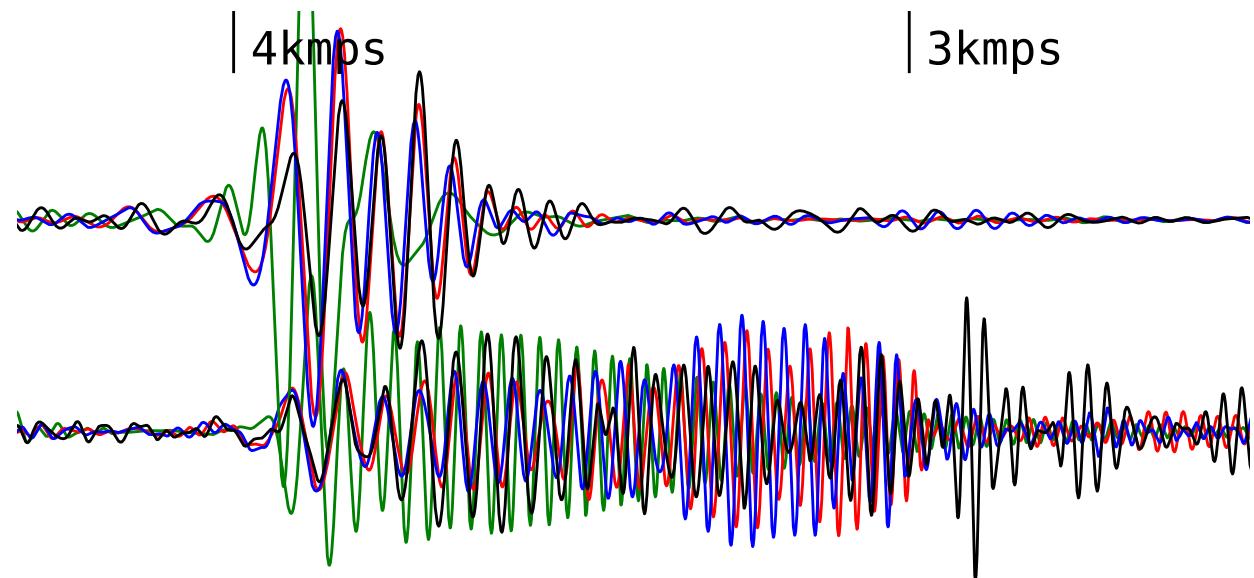
# Comparison to data - record section EU (40 s)



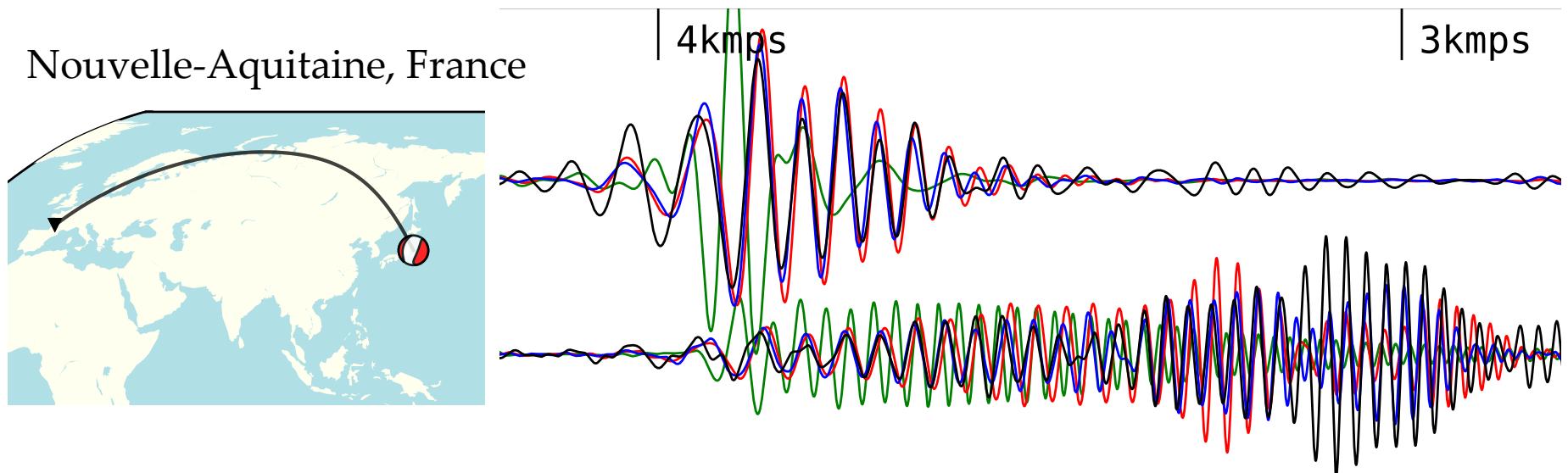
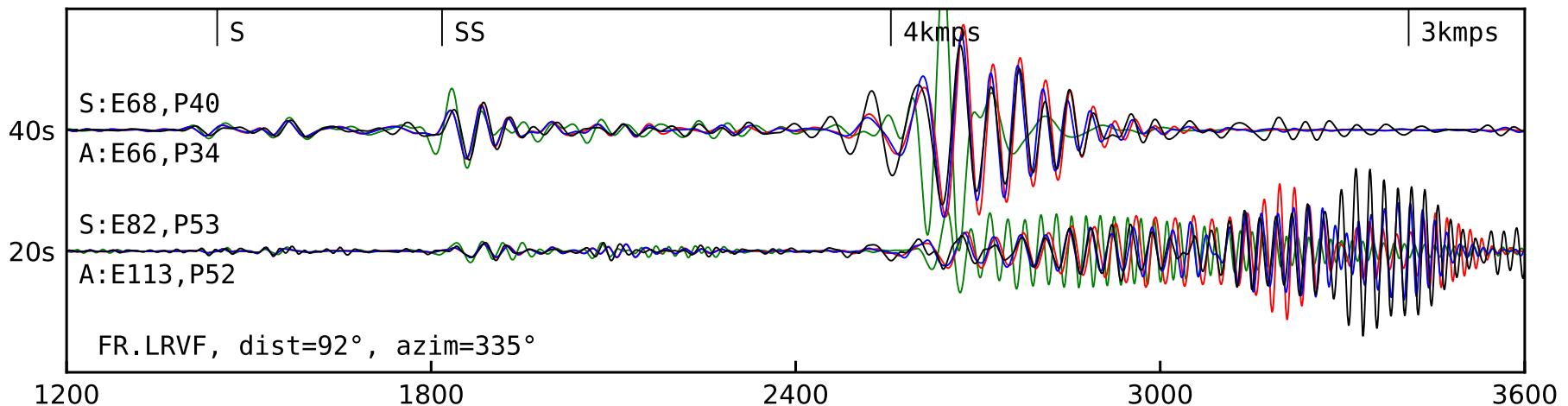
# Comparison to data - single stations



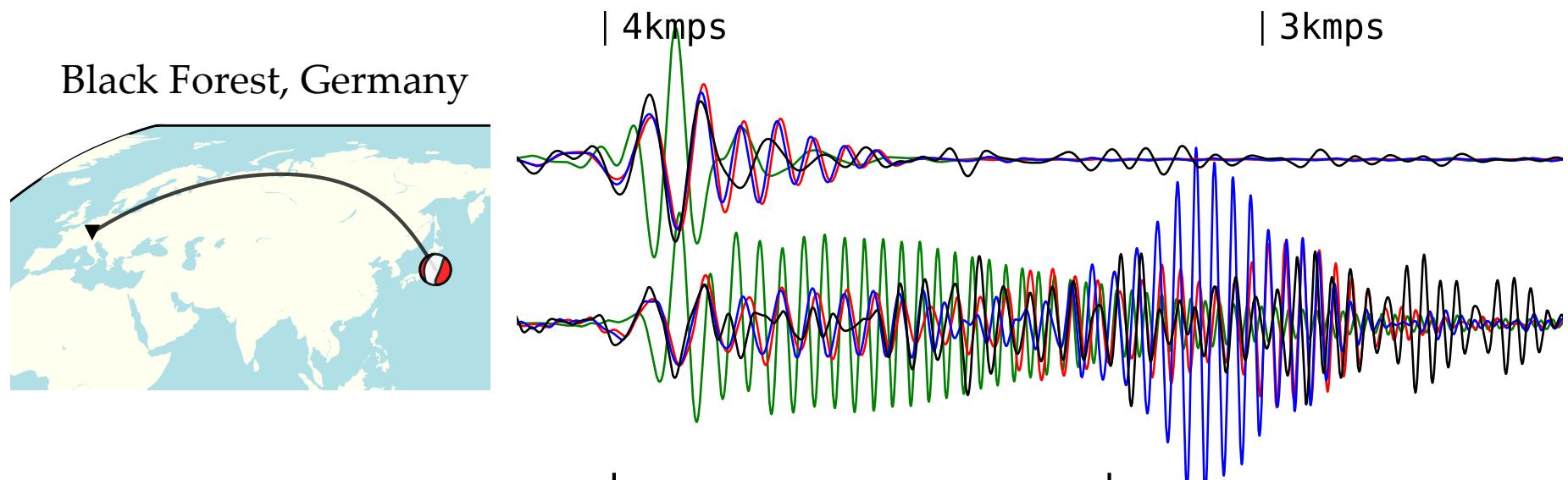
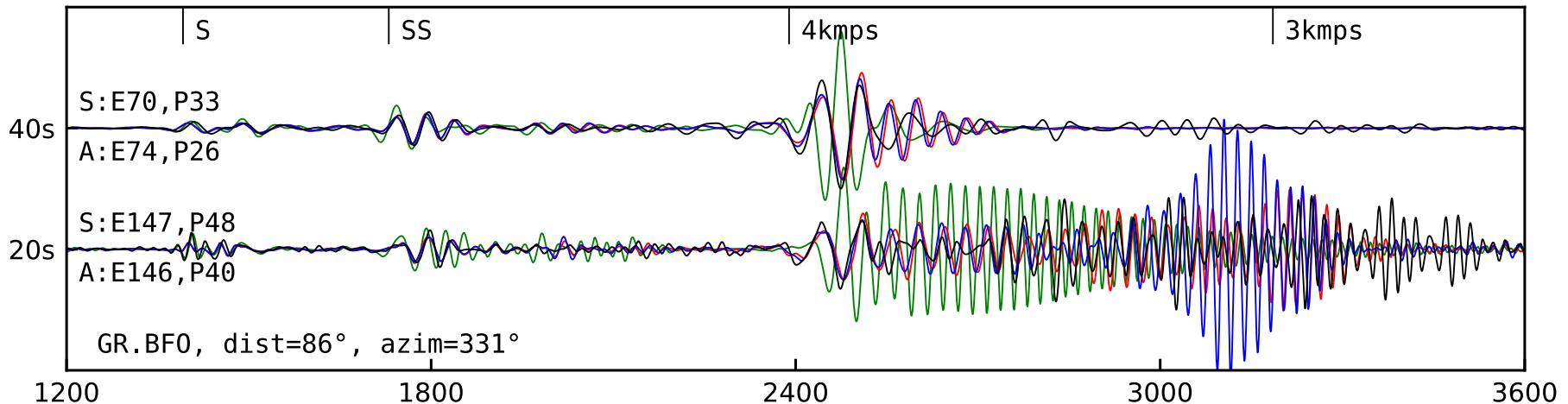
Florina, Greece



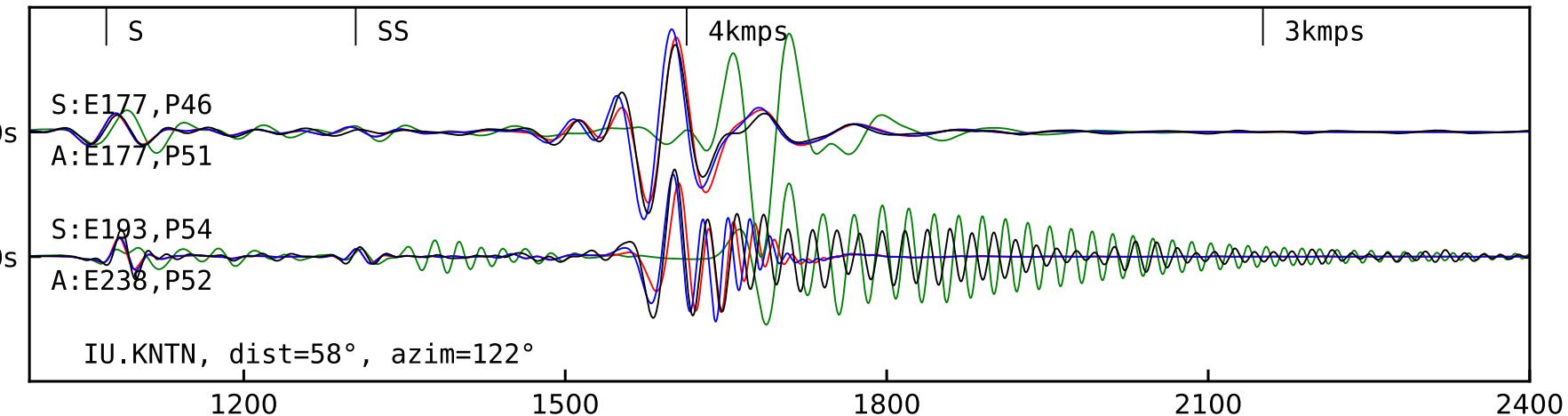
# Comparison to data - single stations



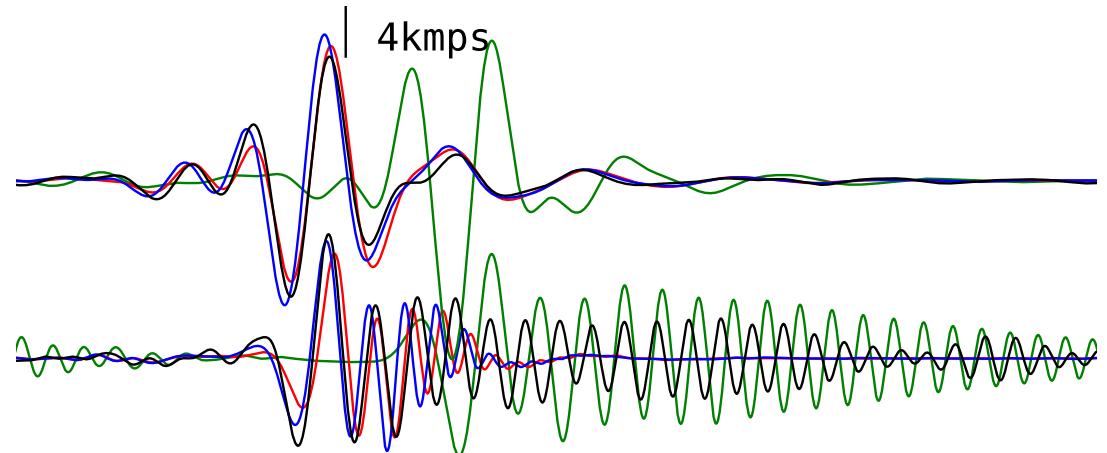
# Comparison to data - single stations



# Comparison to data - single stations



Kanton Island, Kiribati



The load approximation of oceans?

The station is on an island but we place at ocean bottom in the simulation?



P-WAVE: M M M M M M M M M M  
S-WAVE: S S S S S S S S S S



EARTH



# Conclusions

- AxiSEM3D has an equivalent (or better) accuracy as full 3-D SEM such as SPECFEM to simulate surface waves in the state-of-the-art global crustal models, such as Crust 1.0
- AxiSEM3D is 1-2 orders of magnitude faster than 3-D SEM
- Particle relabelling transformation is powerful in handling boundary undulations in terms of material perturbations

# Outlook

- Realistic ocean (subject to theoretical limitations of PRT)
- Local to regional scale extensions
- 3-D sensitivity kernels for surface wave tomography

# **Thanks to**

- Lion Krischer, Michael Afanasiev, Maximilian Rietmann, Christian Böhm and David May
- Archer, the UK Supercomputing Service
- AWE for funding me to attend this meeting

**Thank you for your attention!**